Summarizing the Solution Space in Tumor Phylogeny Inference by Multiple Consensus Trees

Nuraini Aguse*, Yuanyuan Qi* and Mohammed El-Kebir University of Illinois at Urbana Champaign, Department of Computer Science

RECOMB-CCB 2019



*Joint first authorship Accepted at ISMB/ECCB 2019

Additional Challenge in Cancer Phylogenetics



Phylogeny inference from mixtures of/incomplete measurements of leaves

Additional Challenge in Cancer Phylogenetics



Phylogeny inference from mixtures of/incomplete measurements of leaves

Non-uniqueness of solutions: alternative solutions with varying leaf sets

Additional Challenge in Cancer Phylogenetics



Phylogeny inference from mixtures of/incomplete measurements of leaves

Non-uniqueness of solutions: alternative solutions with varying leaf sets

Question: How to summarize solution space \mathcal{T} in order to remove inference errors and identify dependencies among mutations?

Outline

- Problem Statement
 - Previous work
 - Problem statement
 - Combinatorial characterization of solutions
 - Complexity
- Method & Results
 - Exact algorithm
 - Heuristic algorithm
 - Model selection

Phylogenetic Trees vs. Mutation Trees



Infinite sites assumption (ISA): each mutation is introduced once and never subsequently lost

Phylogenetic Trees vs. Mutation Trees



Infinite sites assumption (ISA): each mutation is introduced once and never subsequently lost

Under ISA, a phylogenetic tree may be equivalently* represented by a mutation tree

Solution Space of Lung Cancer Patient CRUK0037

Jamal-Hanjani et al. (2017). New England Journal of Medicine, 376(22), 2109–2121.

Jamal-Hanjani et al. inferred 17 trees for patient CRUK0037



Question: How to summarize solution space in order to remove inference errors and identify dependencies among mutations?

Parent-child Graph: Union of all Edges in ${\mathcal T}$



Parent-child Graph: Union of all Edges in ${\mathcal T}$



The parent-child graph does not capture patterns of mutual exclusivity

Parent-child Graph: Union of all Edges in ${\mathcal T}$



The parent-child graph does not capture patterns of mutual exclusivity

Question: Can we infer a single consensus tree?

Single Consensus Tree: Max Weight Spanning Tree



Single Consensus Tree: Max Weight Spanning Tree



Inaccurate summary for diverse solution spaces

Question: How about inferring multiple consensus trees?





Multiple Consensus Trees (MCT): [ISMB/ECCB 2019] Given trees $\mathcal{T} = \{T_1, ..., T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \rightarrow [k]$ and consensus trees $\mathcal{R} = \{R_1, ..., R_k\}$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum



Multiple Consensus Trees (MCT): [ISMB/ECCB 2019] Given trees $\mathcal{T} = \{T_1, ..., T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \rightarrow [k]$ and consensus trees $\mathcal{R} = \{R_1, ..., R_k\}$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum

Parent-child Distance Function





 T_1

 T_2

Parent-child Distance Function



Parent-child Distance Function



Parent-child distance $d(T_1, T_2)$ is the size of the symmetric difference of the edge sets

Here, $d(T_1, T_2) = |E(T_1) \setminus E(T_2)| + |E(T_2) \setminus E(T_1)| = 4.$

Single Consensus Trees (SCT): [Govek et al., ACM-BCB 2018] Given $\mathcal{T} = \{T_1, ..., T_n\}$, find consensus tree R s.t. $\sum_{i=1}^n d(T_i, R)$ is minimum



Solution Space ${\mathcal T}$

Single Consensus Trees (SCT): [Govek et al., ACM-BCB 2018] Given $\mathcal{T} = \{T_1, ..., T_n\}$, find consensus tree R s.t. $\sum_{i=1}^n d(T_i, R)$ is minimum

> **Theorem:** [Govek et al., ACM-BCB 2018] Max weight spanning arborescences of parent-child graph G_T are solutions to SCT



Single Consensus Trees (SCT): [Govek et al., ACM-BCB 2018] Given $\mathcal{T} = \{T_1, ..., T_n\}$, find consensus tree R s.t. $\sum_{i=1}^n d(T_i, R)$ is minimum

> **Theorem:** [Govek et al., ACM-BCB 2018] Max weight spanning arborescences of parent-child graph G_T are solutions to SCT

Multiple Consensus Trees (MCT): [Aguse et al., ISMB 2019] Given $\mathcal{T} = \{T_1, \dots, T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \rightarrow [k]$ and consensus trees $\mathcal{R} = \{R_1, \dots, R_k\}$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum



Solution Space ${\mathcal T}$

Single Consensus Trees (SCT): [Govek et al., ACM-BCB 2018] Given $\mathcal{T} = \{T_1, ..., T_n\}$, find consensus tree R s.t. $\sum_{i=1}^n d(T_i, R)$ is minimum

> **Theorem:** [Govek et al., ACM-BCB 2018] Max weight spanning arborescences of parent-child graph G_T are solutions to SCT

Multiple Consensus Trees (MCT): [Aguse et al., ISMB 2019] Given $\mathcal{T} = \{T_1, \dots, T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \rightarrow [k]$ and consensus trees $\mathcal{R} = \{R_1, \dots, R_k\}$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum



Solution Space ${\mathcal T}$

Single Consensus Trees (SCT): [Govek et al., ACM-BCB 2018] Given $\mathcal{T} = \{T_1, ..., T_n\}$, find consensus tree R s.t. $\sum_{i=1}^n d(T_i, R)$ is minimum

> **Theorem:** [Govek et al., ACM-BCB 2018] Max weight spanning arborescences of parent-child graph G_T are solutions to SCT

Multiple Consensus Trees (MCT): [Aguse et al., ISMB 2019] Given $\mathcal{T} = \{T_1, ..., T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \rightarrow [k]$ and consensus trees $\mathcal{R} = \{R_{\pm}, ..., R_k\}$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum where $R_{\sigma(i)}$ is max weight spanning arborescence of $G_{\mathcal{T}_{\sigma(i)}}$



Single Consensus Trees (SCT): [Govek et al., ACM-BCB 2018] Given $\mathcal{T} = \{T_1, ..., T_n\}$, find consensus tree R s.t. $\sum_{i=1}^n d(T_i, R)$ is minimum

> **Theorem:** [Govek et al., ACM-BCB 2018] Max weight spanning arborescences of parent-child graph G_T are solutions to SCT

Multiple Consensus Trees (MCT): [Aguse et al., ISMB 2019] Given $\mathcal{T} = \{T_1, ..., T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \rightarrow [k]$ and consensus trees $\mathcal{R} = \{R_{\pm}, ..., R_k\}$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum where $R_{\sigma(i)}$ is max weight spanning arborescence of $G_{\mathcal{T}_{\sigma(i)}}$



Complexity

Multiple Consensus Trees (MCT):

Given $\mathcal{T} = \{T_1, \dots, T_n\}$ and k > 0, find surjective clustering $\sigma : [n] \to [k]$ s.t. $\sum_{i=1}^n d(T_i, R_{\sigma(i)})$ is minimum where $R_{\sigma(i)}$ is max weight spanning arborescence of $G_{\mathcal{T}_{\sigma(i)}}$



Theorem: MCT is NP-hard for general k (by reduction from CLIQUE).

Outline

- Problem Statement
 - Previous work
 - Problem statement
 - Combinatorial characterization of solutions
 - Complexity
- Method & Results
 - Exact algorithm
 - Heuristic algorithm
 - Model selection

Mixed Integer Linear Program

Theorem: MCT is NP-hard for general k (by reduction from CLIQUE).

$\min n(m-1) - \sum_{i=1}^{n} \sum_{s=1}^{k} \sum_{p=1}^{m} \sum_{q=1}^{m} w_{i,s,p}$	q,q
s.t. $\sum_{s=1}^{k} x_{i,s} = 1$	$\forall i \in [n]$
$\sum_{i=1}^{n} x_{i,s} \ge 1$	$\forall s \in [k]$
$\sum_{p=1}^{m} z_{s,p} = 1$	$\forall s \in [k]$
$\sum_{q=1}^m y_{s,p,q} = 1 - z_{s,p}$	$\forall s \in [k], p \in [m]$
$y_{s,p,q} \le b_{p,q}$	$\forall s \in [k], p,q \in [m]$
$\sum_{(p,q)\in\delta^{-}(U)} y_{s,p,q} + \sum_{p\in U} z_{s,p} \ge 1$	$\forall s \in [k], U \subseteq [m]$
$w_{i,s,p,q} \le a_{i,p,q}$	$\forall i \in [n], s \in [k], p, q \in [m]$
$w_{i,s,p,q} \le x_{i,s}$	$\forall i \in [n], s \in [k], p, q \in [m]$
$w_{i,s,p,q} \le y_{s,p,q}$	$\forall i \in [n], s \in [k], p, q \in [m]$
$w_{i,s,p,q} \ge 0$	$\forall i \in [n], s \in [k], p, q \in [m]$
$y_{s,p,q} \le \sum_{i=1}^{n} a_{i,p,q} x_{i,s}$	$\forall s \in [k], p,q \in [m]$
$y_{s,p,q} \ge \sum_{i=1}^{n} a_{i,p,q} x_{i,s} - \sum_{i=1}^{n} x_{i,s} +$	1 $\forall s \in [k], p, q \in [m]$
$\sum_{i=1}^{n} x_{i,s} \ge \sum_{i=1}^{n} x_{i,s+1} + 1$	$\forall s \in [k-1]$
$x_{i,s} \in \{0,1\}$	$\forall i \in [n], s \in [k]$
$y_{s,p,q} \ge 0$	$\forall s \in [k], p,q \in [m]$
$z_{s,p} \ge 0$	$\forall s \in [k], p \in [m]$

Mixed Integer Linear Program

Theorem: MCT is NP-hard for general k (by reduction from CLIQUE).

$x_{i,s} \in \{0,1\}$	Tree T_i is assigned to cluster s
$y_{s,p,q} \ge 0$	Edge (p,q) is present in consensus tree R_s
$z_{s,p} \ge 0$	Vertex p is root of consensus tree R_s

mi	$\ln n(m-1) - \sum_{i=1}^{n} \sum_{s=1}^{k} \sum_{p=1}^{m} \sum_{q=1}^{m} w_{i,s,p,s}$	q
s.1	t. $\sum_{s=1}^{k} x_{i,s} = 1$	$\forall i \in [n]$
	$\sum_{i=1}^{n} x_{i,s} \ge 1$	$\forall s \in [k]$
	$\sum_{p=1}^{m} z_{s,p} = 1$	$\forall s \in [k]$
	$\sum_{q=1}^{m} y_{s,p,q} = 1 - z_{s,p}$	$\forall s \in [k], p \in [m]$
	$y_{s,p,q} \le b_{p,q}$	$\forall s \in [k], p,q \in [m]$
	$\sum_{(n,p)\in S^{-}(U)} y_{s,p,q} + \sum_{r\in U} z_{s,p} \ge 1$	$\forall s \in [k], U \subseteq [m]$
	$(p,q) \in \delta^{-}(U)$ $p \in U$	$\forall i \in [n] \ s \in [k] \ n \ a \in [m]$
	$w_{i,s,p,q} \leq u_{i,p,q}$ $w_{i,s,p,q} \leq x_{i,q}$	$\forall i \in [n], s \in [k], p, q \in [m]$ $\forall i \in [n], s \in [k], p, q \in [m]$
	$w_{i,s,p,q} \leq v_{s,p,q}$	$\forall i \in [n], s \in [k], p, q \in [m]$ $\forall i \in [n], s \in [k], p, q \in [m]$
	$w_{i,s,p,q} \ge 0$	$\forall i \in [n], s \in [k], p, q \in [m]$
	$y_{s,p,q} \le \sum_{i=1}^{n} a_{i,p,q} x_{i,s}$	$\forall s \in [k], p, q \in [m]$
	$y_{s,p,q} \ge \sum_{i=1}^{n} a_{i,p,q} x_{i,s} - \sum_{i=1}^{n} x_{i,s} +$	$1 \qquad \forall s \in [k], p, q \in [m]$
_	$\sum_{i=1}^{n} x_{i,s} \ge \sum_{i=1}^{n} x_{i,s+1} + 1$	$\forall s \in [k-1]$
	$x_{i,s} \in \{0,1\}$	$\forall i \in [n], s \in [k]$
	$y_{s,p,q} \ge 0$	$\forall s \in [k], p, q \in [m]$
	$z_{s,n} > 0$	$\forall s \in [k], p \in [m]$

MILP does not scale well with k and n



Coordinate Ascent (akin to k-means)

- 1. Fix clustering σ at random
- 2. Compute consensus tree R_s for each cluster s
- 3. Reassign each input trees T_i to cluster *s* where $d(T_i, R_s)$ is minimum
- 4. Go to 2

Coordinate Ascent (akin to k-means)

- 1. Fix clustering σ at random
- 2. Compute consensus tree R_s for each cluster s
- 3. Reassign each input trees T_i to cluster *s* where $d(T_i, R_s)$ is minimum

4. Go to 2

	#clusters k	MILP (1 h)	BF (1 h)	CA (1 h)	CA (100 r.)
(9	2	16	16	16	16
(1)	3	16	16	16	16
lla	4	16	16	16	16
sır	5	16	14	16	16
[5]	2	15	13	15	15
n (]	3	13	7	13	13
iun	4	12	0	12	12
Jed	5	10	0	10	10
4)n	2	3	0	3	3
(1	3	0	0	0	0
lge	4	0	0	0	0
laı	5	0	0	0	0

Bayesian Information Criterion





Conclusion

- Introduced the Multiple Consensus Tree (MCT) problem
- Characterized combinatorial structure of optimal solutions
- Showed that MCT is NP-hard
- Presented a mixed integer linear program
- Presented an efficient heuristic and showed that it finds optimal solutions
- Model selection for the number of clusters

Future directions

- Relax infinite sites assumption
- Use medoids rather than centroids